




Source: Ombres et
(Autres)
Pas de Sinal.
Appuyez sur  pour afficher l' slide.











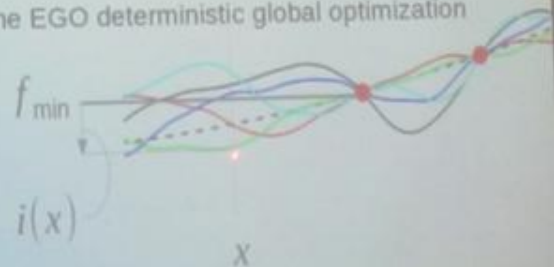
(one point-) Expected improvement

A natural measure of progress : the improvement,

$$I(x) = [f_{\min} - F(x)]^+ \mid F(x) = f(x) \quad , \quad \text{where } [.]^+ \equiv \max(0, .)$$

- The expected improvement is known analytically.
- It is a parameter free measure of the exploration-intensification compromise.

maximization defines the EGO deterministic global optimization algorithm.



$$i(x) \times (\Phi(u(x)) + \varphi(u(x))) \quad ; \quad \text{where } u(x) = \frac{f_{\min} - m_k(x)}{s(x)}$$

(one point-)

A natural measure of progress

$$I(x) = [f_{\min} - F(x)]^*$$

- The expected improvement is
- It is a parameter free measure of progress
- Its maximization defines the algorithm.

f

i

$$s(x) \times |u(x) \Phi(u(x))|$$

(one point-) Exp

A natural measure of progress : the

$$I(x) = [f_{\min} - F(x)]^+ \quad | \quad F(x) = f(x)$$

- The expected improvement is known
- It is a parameter free measure of the compromise.

Its maximization defines the EGO algorithm.

$$f_{\min}$$

$$i(x)$$

$$EI(x) = s(x) \times (u(x)\Phi(u(x)) + \varphi(u(x)))$$

(one point-) Expected improvement

A natural measure of progress : the improvement,

$$I(x) = [f_{\max} - F(x)]^+ | F(x) = f(x) \quad , \quad \text{where } [\cdot]^+ = \max(0, \cdot)$$

- The expected improvement is known analytically
- Is a parameter free measure of the exploration-intensification
- This definition defines the EGO deterministic global optimization



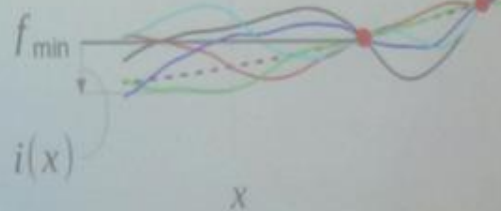
$$I(x) = \Phi(u(x)) + \phi(u(x)) \quad , \quad \text{where } u(x) = \frac{f_{\max} - f(x)}{\sigma(x)}$$

(one point-) Expected improvement

A natural measure of progress : the improvement,

$$I(x) = [f_{\min} - F(x)]^+ \mid F(x) = f(x) \quad , \quad \text{where } [\cdot]^+ \equiv \max(0, \cdot)$$

- The expected improvement is known analytically.
- It is a parameter free measure of the exploration-intensification compromise.
- Its maximization defines the EGO deterministic global optimization algorithm.

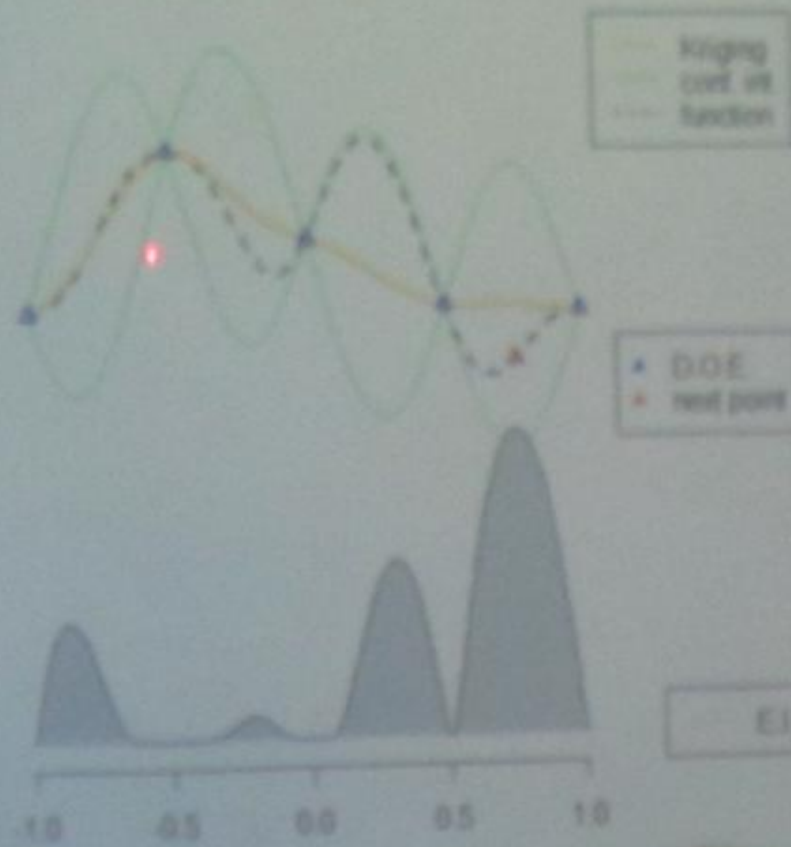


$$EI(x) = s(x) \times [u(x)\Phi(u(x)) + \phi(u(x))] \quad , \quad \text{where } u(x) = \frac{f_{\min} - m_x(x)}{s(x)}$$



maximizes EI,

$$x^{t+1} = \arg \max_x EI(x)$$



then, the kriging model is updated ...

